

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

**B.E.IV (IC)**

**Semester - VII**

**Scheme For Teaching and Examination  
B.E.-IV (Instrumentation & Control ) 7<sup>th</sup> Semester**

<b>B.E.IV (Inst. &amp; Control) - 7th Semester</b>		Teaching Scheme			Examination Scheme						
		L Hrs.	T Hrs.	P Hrs.	Theory Exam		Practical/Quiz/Viva/T.W. etc.				
					University Exam.		University Exam.		Tutorial	Cont. Evaluation	Total Marks
Course	Course No.				Dura- tion	Marks	Dura- tion	Marks			
Digital & Distributed Control system	IC 701 IC	3	1	2	3	100	3	30	25	20	75
System Design	IC 702 IC	3	1	0	3	100	3	0	25	0	25
Transducers and signal Processing	IC 703 IC	3	1	2	3	100	3	30	25	20	75
Process Instrumentation	IC 704 IC	3	1	2	3	100	3	30	25	20	75
Industrial Drives And Control	IC 705 IC	3	0	2	3	100	3	30	0	20	50
Project Preliminaries	IC 706 IC	0	0	4	0	0	0	30*	0	20	50
Industrial Training /Industrial Practice	IC 707 IC	0	0	0	0	0	0	30*	0	20	50
	<b>TOTAL</b>	<b>15</b>	<b>4</b>	<b>12</b>		<b>500</b>		<b>180</b>	<b>100</b>	<b>120</b>	<b>400</b>
Total Contact Hours : 31 Total Marks : 900											

\* Internal Examination, Project Preliminaries, Industrial Training /Industrial Practice is not to be considered as a passing head and evaluation is to be done by the Department

## LIST OF ELECTIVES

Sr. No.	Name of the Subject	Code
	<b>GROUP - I (IC 81X IC)</b>	
1.1	Biomedical Instrumentation	IC 811 IC
1.2	Flight Instrumentation	IC 812 IC
1.3	Parallel Processing & Real Time Operating System	IC 813 IC
1.4	Computer Architecture & PCL card Interfacing	IC 814 IC
	<b>GROUP - II (IC 82X IC)</b>	
2.1	Robotics Engineering	IC 821 IC
2.2	Plant Automation	IC 822 IC
2.3	Process System Analysis	IC 823 IC
2.4	Fuzzy Logic Control & Neural Network	IC 824 IC

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## DIGITAL & DISTRIBUTED CONTROL SYSTEM : IC 701 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	1	2
Examination Scheme Marks	100	25	Cont. Evaluation : 20 Examination : 30

1	<b>BRIEF IDEAS ABOUT DAS :</b> -Introduction of data Acquisition system, -Signal condition of inputs, -single and multi channel DAS, -Computer based controllers, -Programmable controllers, -Present trend in DAS.
2	<b>DISTRIBUTED CONTROL SYSTEMS:</b> -Evolution of DCS, - Data logger, -Design & Specification, -Architecture -Supervisory control with Its architecture, document, merits & demerits, -Direct digital control with Its architecture, document, merits & demerits, - Supervisory Digital Control with Its architecture, document, merits & demerits, -Distributed Control System with Its architecture, document, - Architecture: Hierarchical structure, functional level, data base organization System implementation concept, - System Element: Field, Station, Intermediate stations, Central Computer station, Monitoring & Command facilities, - Data Communication Link : Transfer of process data, Transmission protocols, - Algorithms: Data Acquisition & Signal processing algorithm, Regulatory & Sequential control algorithm, Optimal & Adaptive control, Reliability & Consideration in DCS, - Applications - <u>SOFTWARE</u> : Real time operating system, Communication software, Process Oriented Languages, Applicant Software, Configuration and Parameterization of Software,
3	Comparison of “ $\mu$ XAL” & “TDC 3000” System & Brief Ideas about “FIELD BUS SYSTEM”.

### References:

- (1) Distributed Computer Control for Industrial Automation : By Popovic & Bhatkar, Marcel Dekker
- (2) Distributed Control System Manual : By H.L. Wade, 1993.
- (3) Automation System for Control Data Acquisition : By L.T. Amy, 1992
- (4) Manuals for  $\mu$  XAL ,TDC 3000 and Field bus system.

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SYSTEM DESIGN : IC 702 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	1	0
Examination Scheme Marks	100	25	Cont. Evaluation 00 Examination 00

1	STABILITY CRITERIA OF A CONTROL SYSTEM : - Determination of Stability of Control System, - Routh Hurwitz criteria, - Root Locus & Bodes Plot Tech, - Effect of adding pole/zero on Stability of System, - Nicole chart for stability criteria.
2	BASIC CONCEPTS OF COMPENSATORY DESIGN : - Types, - Method of designing: (1) <u>Time domain Technique for compensation of System:</u> - Lead compensation, - Lag compensation, - Lead & Lag compensation - Warrens and rose method (2) <u>Frequency domain Technique for compensation of System:</u> - Lead compensation, - Lag compensation, - Lead & Lag compensation, - Controller designing ( P, PD, PID etc. )
3	Minor loop design ( feed back loop ) for System compensation.
4	Properties of P.R. function and testing driving point impedance & Admittance.
5	Synthesis of R-C, R-L & R-L-C network & Bott & Duffy method for Synthesis of P/W.

References:

- (1) Control System Engg : By Nagrath & Gopal., New age International pub., 2nd ed.1997
- (2) Introduction to modern P/W Synthesis by : Van Valkenburg.
- (3) Modern Control Engineering : by Ogata., - Prentic Hall of India ltd, 2 nd Edition, 1996.
- (4) Control System Engg : by Eveleigh
- (5) Feed back Control System : By D'Azzo and Houpis.
- (6) Automatic Control System : By Kuo., Prentic hall of india ltd., 7 th edi., 1995.

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## TRANSDUCERS & SIGNAL PROCESSING : IC 703 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	1	2
Examination Scheme Marks	100	25	Cont. Evaluation : 20 Examination 30

1	TRANSDUCERS: - Definition, - Classifications, - Selection Criteria, - Error, - Loading effects, - Basic configuration of control System, - Specification
2	DISPLACEMENT, FORCE VELOCITY, ACCELERATION VIBRATION AND TORQUE TRANSDUCERS : - Displacement in Resistive, Inductive, Eddy , LVDT, Current, Strain gauges, Capacitive, Piezo-electric, Digital, Fiber optics, Flapper nozzle, Laser etc., - Force: - Force Measuring; Electrical load cell, Piezo-electric, Vibrating , - Tachometers, Toothed rotor tachometers, - Photo electric, Stroboscopic principles, - Encoder type Speed Measurement Tech. etc., - Torque - Strain gauges & Others.
3	SIGNAL PROCESSING ELEMENTS & SIGNAL AMPLIFIER : - Phase Sensitive detector.- Absolute Value Ckt., - Peak detector, - rms converter, - V to F converter - Sample & hold Ckt., - F to V converter -V to I Converter & I to V converter,- P to I, I to P converters, Pneumatic converters : Construction, principle, Signal transmission Mode, - Signal conditioning with sine to Square and Square to sine converter, Linearization Ckt. - Instrumentation amplifier and its comparison with A, B, C & AB Amplifier, - Logarithmic amplifier & Antilog amplifier , - Isolation Amplifier using any Technique, - Voltage Control Oscillator, - Phase detector Ckt., - Phase Lock loop operation, , - Square root extractor device, - Frequency Multiplier Ckt.
4	DIGITAL SIGNAL TRANSMISSION : - Data transmission Techniques, - Pulse code formats, - Various Modulation Tech., - Digital Signal Processing.
5	LAN ( Local area Network ) : -Overview of LAN,-Layered Network Architecture,-LAN topology and transmission media, applications

### References:

- (1) Instrumentation devices and System : By Rangan Mani and Sharma., Tata McGraw-Hill Pub., 2nd edi.1998.
- (2) Electronic devices and Ckt. an Introduction : By Motter Shed., Prentic hall of India pvt. Ltd., 19 th edi., 1997.
- (3) Measurement System : By E.O. Doebelin., -New York Mcgrawhill Pub.Co . 4 th Edition 1990.
- (4) Process Control Instrumentation Technology : By C.D. Jonson.,- -Prentic hall of India Pvt.Ltd., 4 th Edition1997.
- (5) Op-Amps and linear integrated circuits. Ramakant Gaykwad: Prentice Hall of India, IIIrd Ed. (1997).

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

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Semester - VII

## PROCESS INSTRUMENTATION : IC 704 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	1	2
Examination Scheme Marks	100	25	Cont. Evaluation : 20 Examination : 30

1	<b>PROCESS DYNAMICS :</b> - Process Variables, Different types of lags, - Mathematical Modeling of different process such as level, flow, temp, pressure etc.- Effect of Valve positioner changes.
2	<b>CONTROLLER MODES :</b> - Principles of Proportional, Integrals, derivative and composite modes (PI, PD, PID etc.) -Working operation with diagram of analog and digital controller like Proportional, Integrals, derivative and composite modes and Pneumatic controller for different modes. - Gain Setting Kp, Ki, Kd from response of System, - Proper Applications for individual Controlling mode
3	<b>ANALYSIS AND PROPERTIES OF LOOP AND SELECTION OF CONTROLLER :</b> - Control Loops Characteristics for Flow, Pressure, Level & Temp., - Linear & Non. linear Controllers, - Performance Criteria.
4	<b>MULTI LOOP AND MULTIVARIABLE PROCESS CONTROL SYSTEM :</b> - Feed back Control, - Feed forward Control Scheme., - Cascade Control Scheme, - Ratio Control mode, - Selective Control Scheme., - Multivariable type controlling Scheme, - Coupling and decoupling Control System
5	<b>ADAPTIVE CONTROL SYSTEM :</b> - Introduction,- Standard Approaches, -Self adoptive Control,-Predictive, - Optimization with random disturbances
6	<b>AUTO-TUNING OF PID CONTROLLERS :</b> - Introduction, - PID Control action, - Process Dynamics, - Design of PID Controllers, - Auto tuning.

### References:

- (1) Process Control : By A. Pollard
- (2) Applied Instrumentation in process industries. : By Andrews -, Houston Gulf Pub.co. II<sup>nd</sup> edi. 1979.
- (3) Process Control System : By F.G. Shinsky.
- (4) Process Control : By Liptak. Oxford:/ Butterworth / Hein mann Ltd., - III rd Edition,1999.
- (5) Automatic Tuning of PID Controllers : By K.J. Astrom and R. Haggjund.
- (6) Multivariable Process Control : By P.B. Deshpande.
- (7) Process Control Instrumentation Technology : By C.D. Johnson. - -Prentic hall of India Pvt.Ltd., 4 th Edition, 1997.

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## INDUSTRIAL DRIVES AND CONTROL : IC 705 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	0	2
Examination Scheme Marks	100	00	Cont. Evaluation : 20 Examination : 30

1	<b>INVERTORS :</b> - Line Commuted and forced commuted invertors, - Series and parallel invertors, - Design of commutative components.
2	<b>CHOPPER :</b> - Principle, - Types of Mechanical and electrical choppers, - RL Load Classification, - Chopper ckt; Step up,- John's. Step up chopper, - A.C. choppers.
3	<b>CONVERTERS &amp; CYCLO CONVERTERS :</b> - Operation of half controlled and fully controlled bridge converters, - Effects of Inductance and free-wheeling diode, - Dual Converters, - Protective ckt for over voltage and over current, - Operation of cyclo converters for half and full bridge and Merits / De merits over converter bridge.
4	<b>D.C. DRIVE CONTROLLING :</b> - Speed control using current & Speed feed back, - using field current and circulating current method. - $\emptyset$ phase H / W converter ckt., - $\emptyset$ phase F / W converter drive ckt., - 3 $\emptyset$ phase drives ( H / W & F / W ), - chopper operated drives.
5	<b>A.C. DRIVE CONTROLLING :</b> - Speed and torque char. of A.C. Motor, - Different method of controlling Stator and rotor parameters, - Stator Voltage control, - Rotor resistance variation, - Rotor frequency control.
6	<b>STEPPER MOTOR &amp; ITS CONTROL DEVICES :</b> - Construction, - Principle, - Control on MP base firing ckt operation, - Industrial Applications.

### References:

- (1) Power Electronics : By P.C. Sen. - -New Delhi Tata Mcgrawhill, 2nd edi. 1997.
- (2) Power Electronics ckt devices and Application : By M.H. Rashid, Prentice Hall of India, 2nd edi., 1997
- (3) Thyristors theory and Application : By R. K. Susandhi and K.K. Susandhi, New age International, 2nd edi., 1997
- (4) An Introduction of thyristors and their applications : By M. Ramamoorthy, Affiliated east /west press. -2nd edi., 1998.
- (5) Thyristorised Power Controllers by Dubey, Doradla, Joshi & Sinha . New age international, 1996
- (6) Power Electronics: By P.S. Bimbhra, Khanna pub., 2nd edi. , 1998.

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## PROJECT PRELIMINARIES : IC 706 IC

	Lecture	Tutorial	Practical
Teaching Hours	0	0	4
Examination Scheme Marks	000	00	Cont. Evaluation : 20 Examination : 30

### Objectives :

To develop creativity of a student in his area of specialisation and allied subject.

To develop ability for handling of the equipment and selection of proper instruments, adoption of standard test procedure and interpretation of the result.

### Curriculum :

Under the subject the student is suppose to carry out Preliminary literature survey, Select the project, Work out the feasibility of the project, Design and develop circuit and block diagram lay-out, Selection of component and preparation of specification. Part of the project must be fabricated and tested, Report writing.

**Note :** The same project shall be continued in VIII sem., where he is suppose to fabricate and test the entire project to the satisfactory operation.

## GROUP DISCUSSION : IC 706 IC

### B.E. IV (IC) 7th Semester

#### Scheme:

- \* Minimum Five Discussion are arranges on different Topics during term ( On odd Saturday )and Each discussion contribute Equal Marks
- \* First three topics will be given before Discussion and Last two Discussion on the spot on Current topics.
- \* Per group maximum **Ten Students** are considered.

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INDUSTRIAL TRAINING/ INDUSTRIAL PRACTICE : IC 707 IC

	Lecture	Tutorial	Practical
Teaching Hours	0	0	0
Examination Scheme Marks	000	00	Cont. Evaluation : 20 Examination : 30

**INDUSTRIAL TRAINING** : The student will find suitable organisation or industry oriented in the field of Instrumentation , Computer, Industrial electronics, R & D activities, Instrument servicing and manufacturing unit, etc. and undergo through the training for the 3/4 weeks during vacation after 6th semester.

The student will prepare the training report and defend the oral / viva examination in 7th semester.

**OR**

**INDUSTRIAL PRACTICE** : The students electing this option will be assigned the task by the department faculty. This may consist of one or more activities listed below :

- 1) Data collection,
- 2) Report preparation on subject assigned
- 3) Trouble shooting of problem
- 4) Preparation of P & I diagram for given process
- 5) Installation / Maintenance detail collection
- 6) Group discussion on given topic
- 7) Competitive tests , etc.

The term work will consist of a report prepared by student on the activity carried out by him during the term and oral presentation

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## INDUSTRIAL TRAINING : ID 708 IC

- Work Profile:** \* Through Industrial Training, Students are aware from Industrial Atmosphere and real practical system, plant trouble shouting etc.  
\* During Vocational training, RESPONSE SHEET per student from industry or section head with Remarks will be considered  
\* Preparation of "Training Report" on particular task which will be given by industrial person during training.  
\* Training are arrange during vacation period of Sem. VI & Sem. VII.
- Evolution :** \* 50% Weightage of total marks on base of response sheet & Training report .  
\* 50% Weightage of total marks on base of Interview/ Oral Which will be taken by Industrial Expert.

### 2.2 Power Plant Instrumentation

1	<b>POWER PLANT:</b> Unit Overview, types of boilers, turbines, generators, condensers, variable speed pumps and fans, material handling system.
2	<b>BOILER INSTRUMENTATION:</b> Control and, Combustion control (burner management), drum level control, steam temperature and pressure control, sequence event recorders, supervisory control, data acquisition system, optimization techniques (e.g. fuzzy logic)
3	<b>TURBINE INSTRUMENTATION:</b> Condition monitoring and power distribution instrumentation.
4	<b>HYDRO-ELECTRIC POWER GENERATION:</b> Pollution and effluent monitoring and control.
5	<b>MISCELLANEOUS:</b> Power generation using non-conventional energy, power plant safety and redundancies.

### References:

- (1) Distributed Computer Control System : by Popovic and Bhatkar, Marcel Dekker.
- (2) Energy Handbook : by Considine D.M. , McGraw Hill.
- (3) Solar Energy Technology Vol. I and II : by Dickinson and Cheremisonoff, M. Dekker, 1980.
- (4) Process Control : by Liptak, Chilton Book Co.
- (5) Process/Industrial Inst. & Controls hand book : by Considine D.M.- 4 th Edition McGraw Hill. @1993.

## 2.4 Fluid Mechanics

1.	<p><b>INTRODUCTION AND PROPERTIES OF FLUIDS:</b></p> <p>Scope and applications of Fluid Mechanics : Definition of Fluid, Newton’s law of viscosity, Classification of Fluids-Newtonian and Non-Newtonian fluids, ideal and real fluids; SI system or units; Physical properties of fluids- Mass density, specific weight, specific volume, Relative density, Dynamic and Kinematic viscosity, compressibility, Bulk modulus of elasticity, Cohesion, adhesion, surface tension, capillarity Vapour pressure, cavitation.</p>
2.	<p><b>FLUID STATICS:</b></p> <p>Basis of fluid statics pressure at a point, Pascal’s law, Pressure-density-height relationship, Measurement of pressure-Manometers, pressure gauges, transducers; Hydrostatic pressure on plane and curved surfaces, centre of pressure, pressure diagrams. Engineering applications related to hydrostatic pressure.</p>
3.	<p><b>FLUID KINEMATICS:</b></p> <p>Methods of describing the motion of fluid, Velocity and acceleration of fluid particles; Types of flow-steady and unsteady, uniform and non-uniform, laminar and turbulent, one-two and three dimensional flows, Streamlines, path lines and streak lines, stream tubes. Equation of continuity for one-dimensional flow in Cartesian coordinates; Circulation and vorticity, rotational and irrotational motions; Concepts of velocity potential, stream function and flow net; Free and forced vortices.</p>
4.	<p><b>FLUID DYNAMICS:</b></p> <p>Forces acting on fluid mass on motion; Various forms of equations of Motion, Euler’s equation of motion along a stream line, Bernoulli’s equation along a stream line for incompressible flow as an integration of Euler’s equation of motion. Linear momentum equation; Applications of continuity equation, Bernoulli’s equation and momentum equation to flow measuring devices such as pitot tube, Venturimeter, orificemeter, nozzle meter, bend meter, rotameter, anubar system, current meter, electro-magnetic meters, orifices mouthpieces, notches and weirs.</p>
5.	<p><b>DIMENSIONAL ANALYSIS AND MODEL STUDIES:</b></p> <p>Dimensions of physical quantities, Dimensional homogeneity, Dimensional analysis using Buckingham’s Theorem method; Important dimensionless parameters and their significance.</p> <p>Model analysis: Geometric, kinematic and dynamic similitude; various model laws.</p> <p>Applications of dimensional analysis and model studies to fluid flow problems.</p>
6.	<p><b>FLOW THROUGH PIPES:</b></p> <p>Laminar flow in circular pipes- Hagen-Poiseuille equation; Laminar flow between parallel surfaces, Stokes’ law, Various methods of measurement of viscosity, Lubrication mechanism; Flow through porous media, Darcy’s law.</p> <p>Turbulent flow in pipes: Velocity and pressure fluctuations in turbulent flow; Semi-empirical theories to estimate shear stresses in turbulent flow, Prandtl’s universal velocity distribution equation for turbulent flow in pipes.</p> <p>Darcy- Weisbach equation for loss of head due to friction, Variation of friction</p>

	factor in laminar and turbulent flow Moody's diagram, Minor losses, Various arrangements of pipes-simple, series and parallel pipes, siphon, Transmission of power through pipes. Water hammer phenomenon- rise of pressure for gradual and sudden closure of valve. Introduction to three-reservoir problem and pipe network. Uniform flow in open channels - Use and Manning and Chezy's formulae.
7.	<b>FLOW AROUND SUBMERGED OBJECTS:</b> Concept of boundary layer, Separation of boundary layer, concept of drag and lift , Pressure distribution around submerged objects Cylinder's and aerofoil. Variation of drag Co-efficient with Reynold's number.
8.	<b>HYDRAULIC MACHINERY AND INTRODUCTION TO COMPRESSIBLE FLOW:</b> Introduction to hydraulic turbines and centrifugal pumps. Basic equations of fluid flow as applied to compressible flow; Energy equation for isothermal and adiabatic processes; Propagation of elastic wave in fluid medium, velocity of sound Mach Number; stagnation point and stagnation pressure, Measurements in Compressible flow; pitot static tube, Hot wire anemometer.

**References:**

- (1) Fluid Mechanics : by Streetes/ Wylie.
- (2) Theory of Application of fluid Mechanics : by Subramanyam.
- (3) Fluid Mechanics : by Gaarde Mirajgaonkar.
- (4) Hydraulics and Hydraulic Machinery : by. Madras.
- (5) Fluid Mechanics with Engineering Applications :by Daughesty.
- (6) Fluid Mechanics by Shortri.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

Scheme For Teaching and Examination  
B.E.-IV (Instrumentation & Control ) 8<sup>th</sup> Semester

B.E.IV (Inst. & Control) - 8th Semester		Teaching Scheme			Examination Scheme						
		L Hrs.	T Hrs.	P Hrs.	Theory Exam		Practical/Quiz/Viva/T.W. etc.				
					University Exam.		University Exam.		Tutorial	Cont. Evaluation	Total Marks
Course	Course No.				Dura- tion Hrs.	Marks	Duration Hrs.	Marks			
Modern Digital Control System	IC 801 IC	3	1	0	3	100	0	0	25	0	25
Instrumentation Systems & Interfacing	IC 802 IC	3	1	2	3	100	3	30	25	20	75
Projectplanning estimation & Quality Systems	IC 803 IC	3	0	2	3	100	3	30	0	20	50
Elective - I	IC 81X IC	3	0	0	3	100	3	0	0	0	0
Elective - II	IC 82X IC	3	0	0	3	100	3	0	0	0	0
Project	IC 806 IC	0	0	8	0	0	0	120	0	80	200
Seminar	IC 807 IC	0	2	0	0	0	0	30	0	20	50
	<b>TOTAL</b>	<b>15</b>	<b>4</b>	<b>12</b>		<b>500</b>		<b>210</b>	<b>50</b>	<b>140</b>	<b>400</b>
Total Contact Hours : 31											Total
Marks : 900											

- Note :**
1. Students have to opt one subject each from Group-I and Group-II .
  2. Seminar is not to be considered as a passing head and evaluation is to be done by the Department.

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Semester - VIII

## MODERN DIGITAL CONTROL SYSTEM : IC 801 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	1	0
Examination Scheme Marks	100	25	Cont. Evaluation : 00 Examination : 00

1	INTRODUCTION OF LINEAR CONTROL SYSTEM:- -Type of control systems , -Servomechanism, -Development of automatic control system, -Sampled & Digital control system, -Multivariable system & It's application.
2	NON-LINEAR SYSTEM: -Types of nonlinearity, -Characteristic, -Piecewise linearisation,-Describing function for nonlinear system & It's application for different systems.
4	SAMPLE DATA SYSTEM: -Principle, -Signal reconstruction, -Pulse transfer function, -Transient response of System (1 <sup>st</sup> & 2 <sup>nd</sup> ) for Various Inputs, -Z - Transformation (zee transform) and Its advantages over Laplace transform, -Inverse Z transformation, -Modified Z transform, -Mapping from S plane to Z plane, -Stability criteria in Z transform, -Design of W plane, -Brief Ideas of Designing of PID Controller.
5	STABILITY ANALYSIS FOR NON-LINEAR SYSTEM: -Equilibrium state stability, -Stability approach by Describing function, -Limit Cycle, -Construction of Phase Trajectory, -Analysis by Phase Plane method, -Isocline method, -Delta & Pell's methods, -Liapunov Stability Concepts,
6	- DIGITAL SIGNAL PROCESSING & IT APPLICATION : -DSP processor architectural features, Hardward and modified hardward architecture, Computational units , memory interfacing and brief about ADSP 21 XX Processor. - DSP Application : Digital PID, Adaptive and fuzzy Controller .

### References:

- (1) Control System Engg. By J.Nagrath & M. Gopal - - New age International, II nd Edition 1997.
- (2) Automatic Control System By B.C. Kuo , New Delhi / Prentic hall of india ltd., VII th Editiion 1995.
- (3) Modern control Engg. By M. Gopal, New Delhi / New Age International Ltd., IInd Editiion @1996..
- (4) Digital & Sample Data Control System By J. T. TON
- (5) Digital Control System BY Houpis & Lamont
- (6) Theory and application of digital signal processing : by Lawrence R. Rabiner and Bernold Gold , Prentice Hall-1975.
- (7) Introduction to digital signal processing : by R. Kuo - McGraw Hill International edi,1988.

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Semester - VIII

## INSTRUMENTATION SYSTEMS AND INTERFACING : IC 802 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	1	2
Examination Scheme Marks	100	25	Cont. Evaluation : 30 Examination : 20

1.	<b>LANGUAGE OF ELECTRICAL MEASUREMENTS:</b> Charge, voltage and current, Electrical units- sinewaves, frequency and phase, Average and RMS values-Language of Digital Measuring systems.
2.	<b>ELECTRICAL LABORATORY PRACTICE:</b> Safety, Grounds, Circuit protection devices- cables, connectors, switches and relays, Input impedance and loading, power transfer and impedance matching.
3.	<b>INTERFERENCE SIGNALS &amp; THEIR ELIMINATION OR REDUCTION:</b> Capacitive interference, Inductive interference and shielding, Electromagnetic interference and shielding, Conductively coupled interference, Group-loop (common mode) interference, Input guarding to reduce around loop interference, Internal noise.
4.	<b>INTERFACING OF ANALOG TO ANALOG INSTRUMENTS, ANALOG TO DIGITAL INSTRUMENTS:</b> Analog systems, Miscellaneous aspects of Analog Signal conditioning, Analog signal transmission, Analog to Digital systems, Sample and hold circuits, Multiplexers, Analog to Digital, Data Acquisition System configuration.
5.	<b>DIGITAL TO DIGITAL INTERFACING:</b> Language of Digital data transmission, Binary coded decimal interface, IEEE-488 bus, CAMAC interface, Serial, Asynchronous interfacing, Data line monitors, RS-232c standards , 20mA current loop, Universal Asynchronous Receiver-transmitter, Pre-assembled Interface sub-systems, Long -distance Data transmission.
6.	<b>HART PROTOCOL:</b> Method of operation, protocol structure, operating conditions.

- (1) "Distributed Computer Control System" by Popovic and Bhatkar, Marcel Dekker
- (2) Distributed Control System Manual : By H.L. Wade, 1993.
- (3) Automation System for Control Data Acquisition : By L.T. Amy, 1992
- (4) Student Reference manual for Electronic Instrumentation Laboratories : by Stanely wolf & Richard F. M. Smith, Prentice Hall (I) pvt. ltd., 1999

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

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Semester - VIII

## PROJECT PLANNING ESTIMATION & QUALITY SYSTEMS : IC 803 IC

	Lecture	Tutorial	Practical
Teaching Hours	3	0	2
Examination Scheme Marks	100	0	Cont. Evaluation : 20 Examination : 30

1	PROJECT IMPLEMENTATION AND COST ESTIMATION : Activity V/s documents, manpower planning, project time schedule, cost heads and estimation.
2	PROJECT ENGINEERING AND DOCUMENTATION : Document system, standard symbols and legends, process flow sheet, P & I diagrams, control schematics, instrument list, interlock diagrams, plant G.A. diagram, power/ air distribution, cable engineering, loop schematics and termination diagrams, installation sketches and bill of material, control system documentation.
3	SPECIFICATIONS, CONFIGURATION, AND DESIGN CRITERIA : Degree of automation, manpower matching, instrument specification sheets, area classification and instrument selection, control system specification including control panel, PLC and DCS, subsystem and integration, configuration diagrams.
4	PROJECT MONITORING AND CONTROL : PERT/ CPM techniques, project bar chart, tendering procedure, bid evaluation and procurement procedures, project coordination, multi -agency interaction.
5	TEST PROCEDURES, INSTALLATION AND COMMISSIONING : Factory acceptance and site acceptance test, inspection reports and check list, installation and commissioning, control schedule and site activities upto handover, post installation maintenance, spares management, annual maintenance contract.
6	QUALITY SYSTEMS : Introduction to International quality systems, Quality system requirements, Procedures and Quality system documentation , Implementation and certifying agencies.

### References :

- (1) Applied Instrumentation in Process Industries, Vol.iii ,by Andrew and Williams, Gulf pub ., 2nd edition, 1979
- (2) Process control hand book by Liptak, 3 rd edition, 1999
- (3) Practical Process Instrumentation and Control, Vol II by Jay Mal.
- (4) Batch Control System ( ISA ) by T. G. Fisher.
- (5) ISO- 9000 Concepts, Methods & Implementation : By Tapan B. Bagchi - Wheeler pub.
- (6) ISO- 9000 Guidelines for the chemical & process industries : By ASQC ( American Society of Quality Control ) - Ben Johnson pub.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

ELECTIVE GROUP - I

## 1.1 IC 811 IC : BIOMEDICAL INSTRUMENTATION

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1	<b>BIOSIGNALS AND RECORDING :</b> - Source of bioelectric signal, Resting & action potential potential , ECG leads Placement, Einthoven angle, Electrocardiogram, Vector, phono cardiography, Electromyogram, Electroencephalograph, Electrodes for ECG ,EEG,EMG,Basic requirements of Amplifier, interference reduction ckt., Active filters, noise rejection technique.
2	<b>BIOMEDICAL EQUIPMENT :</b> - ECG, EEG, EMG, X-Ray machine, Cardiac pacemaker, Hemodialysis machine, Diathermy unit, LASER in surgery, Blood gas analyzer, Blood cell counter.
3	<b>RESPIRATORY SYSTEM &amp; ELECTRICAL SAFETY :</b> -Physiology, Tests and instrumentation for breathing mechanics, Artificial respiration - Electric shock hazard, Leakage current, Physiological effect of electric current safety codes for medical equipment, Accident prevention method, Test instruments.
4	<b>BIOMEDICAL TELEMETRY:</b> -Single & multi channel wireless telemetry, Telephone telemetry.
5	<b>ULTRASONIC IMAGING SYSTEM :</b> - Generation and detection of ultrasonic waves, ultrasonic scanner, Biological effect.
6	<b>COMPUTERS IN BIOMEDICAL :</b> -Interfacing with medical equipments, Analysis of ECG, Patientmonitoring system, Catheterisation laboratory, Clinical laboratory automation.

### References:

- (1) Hand book of Biomedical Instrumentation - R.S. Khandpur, Tata Mcgrawhill, 1999.
- (2) Introduction to Biomedical Equipment Technology - J.J. Carr and J.M. Brown John Wiley & Sons.
- (3) Medical Instrumentation, Application & Design by John Webster, John Wiley & sons, 3rd edi., 1999
- (4) Biological Control System Analysis - J.H. Milseum McGraw Hill.
- (5) Principles of Applied Biomedical Instrumentation - Geddes and Backer John Wiley & Sons. 3rd edi., 1989.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

## 1.2 IC 812 IC : FLIGHT INSTRUMENTATION

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1	Atmosphere, aerospace transducers for measurement of flight parameters, aircraft instruments to measure speed, altitude outside air temperature and pressure, various types of manometers, pitot and static tubes, yaw and pitch meters, anemometers, measurement of velocity field, pressure field, lift, drag and moments.
2	Automatic flight control system, various types of active control applications, flight test instrumentation, gyroscopic principle and instruments, wind tunnels and their utility to aeronautical and other fields, flow visualization techniques in wind tunnels.
3	Flight data acquisition and recording systems, general layouts and operation block diagrams of power plant, study of typical fuel control systems, hydraulic servo systems.
4	Microprocessor/computer based flight control and instrumentation systems, autopilot, fly-by-wire, determination of flight characteristics such as maximum speed, best climb rate.

References:

- (1) Modern Aviation Electronics. By A.Helpfric, Prentice Hall, 1984.
- (2) Avionics Navigation System. By M.Kaytorm and W.R.Fried, Wiley 1964.
- (3) Air-craft Instruments. By M.Coulthard, Pitman, 1952.
- (4) Control of Aircraft and Rocket Power Plants. By Sobby and Sugg. Wiley. 1963.
- (5) Control system Components. By Gibson and Tutor, McGraw Hill.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

## 1.3 IC 813 IC : PARALLEL PROCESSING AND REAL TIME OPERATING SYSTEM

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1.	Definition of parallel computer, evolution of parallel computers. Types of parallelism, intertask dependencies.
2	Structure of parallel computers, pipeline, array, shared memory multiprocessor, message passing multiprocessor, performance of parallel computers, features of parallel computers, data flow concepts, computing language, parallel processor applications.
3	Real time operating system : Introduction, types of operating systems, requirements of general RTOS, input output management, task scheduler, storage management and kernel structure of RTOS.
4	Neural networks and computing.
5	Introduction to expert systems and applications.

### References:

- (1) Digital Control System. By Houpis and Lamont, McGraw Hill, 1985.
- (2) Operating Systems Principles. By Hansen P.B., Prentice Hall, 1973.
- (3) Elements of Parallel Computing. By V.Rajaraman, PHI, 1990.
- (4) Computer Architecture and Parallel processing. By Hwang Kai, McGraw Hill, 1985.
- (5) Introduction to Parallel Processor and Distributed Control. By Sharp.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

## 1.4 IC 814 IC : COMPUTER ARCHITECTURE AND PCL CARD INTERFACING

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1	INTRODUCTION OF DIGITAL COMPUTER : - Basic ideas about Mother Board and I/O cards.
2	ARCHITECTURE OF 8086 AND ITS PROGRAMMING : - Basic elements of 8086 : ALU, Stack, Addressing Mode, Operating Mode, Pipelining process, Flopy & hard disc driver card, Display card - other controllers, interfacing port. ( Serial & Parallel ) etc., - Arithmetic logical Assembly level programming of 8086. - Memory I/O, Brief introduction about 80186,80286,80386 etc. Ethernet card, other cord interfacing with CPU.
3	ARCHITECTURE OF 6800 AND ITS FAMILY : - Basic elements of 6800 : ALU, Stack, Addressing Mode, Operating Mode, Pipelining process - other controllers, interfacing port. ( Serial & Parallel ) etc., - Arithmetic logical Assembly level programming of 6800. - Memory I/O, Brief introduction about 68000 , Zilog-80 etc.
4	LOCAL AREA N/W COMMUNICATION TECHNIQUES : - Concept, topologies, transmission Media, Basis of queuing theory for LAN, Network interconnection, reliability, Security and Applications.
5	TYPES OF PLC CARDS AND IT'S RELEVANT APPLICATIONS : - 8 - channel multiplexing and demultiplexing card., - High performance DAS ( Data Acquisition card ) , - EPROM programmer card, Motor driver card , - 8 channel isolated thermocouple cards etc..

### References:

- (1) Microprocessor and Interfacing, Programming and Hardware By Douglas V. Hall, Tata Mcgrawhill, 2nd edi., 1999.
- (2) Microprocessor System : The 8086/8088 Family, Architecture, Programming and Designing By Glen A. Gibson & Yu Cheng Liu., Prentice Hall of India, 2nd edi., 1996.
- (3) The 8088 and 8086 microprocessor programming, Interfacing, Software, Hardware Application By Triebel and Avtarsingh., Prentice Hall of India, 1995.
- (4) Local Area Network : By Gred E Keiser., Tata Mcgrawhill, 1999
- (5) The 8086/ 8088 Family : Design, Programming & Interfacing by John Uffenback, Prentice Hall of India, 1995.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

ELECTIVE GROUP - II

## 2.1 IC 821 IC : ROBOTICS ENGINEERING

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1	INTRODUCTION ABOUT ROBOTICS & ITS TECHNOLOGY : - Automation and Robotics, - Robotics in science Fiction, - Brief history of robotics, - Robotics market and future prospects, - Robot anatomy, - Work Volume, -Robot drive System, - Control System & dynamic performance, - Precision of Movement, - End effectors, - Sensors.
2	ROBOT MOTION ANALYSIS AND CONTROL : - Introduction to manipulator Kinematics, - Homogeneous Transformations & Kinematics, - Manipulator path control, - Dynamics, - Control Configuration.
3	ROBOT END EFFECTORS : - Types of end effectors, - Mechanical & other Grippers, - Tools as end effectors, - End effector interface, - Selection of gripper and design.
4	SENSORS IN ROBOTICS : - Transducers and sensors in robotics, - Tactile Sensors, - Proximity and range sensors - Miscellaneous Sensors , - Use of Sensors in Robotics.
5	ROBOT PROGRAMMING & LANGUAGE : - Method of robot programming, -Leadthrough programming method, -Robot program as path of space, -Motion interpolation , WAIT SIGNAL, DELAY and branching command, -Limitations and capacities of lead through method, -Robot language structure and textual language, -Motion ,end effector and sensors commands.
6	APPLICATION OF ROBOTICS : - Processing Operation , - Material transfer and machine loading and unloading.

### References:

- (1) Industrial Robotics : by Mikell P. Groover , Mitchell Weiss, Roger N. Nagel and Nicholas G. Odrey Mc Graw - Hill., 1986.
- (2) Fundental of Robotics Analysis and control : by Robet J. Schilling - Prentice Hall,1996.
- (3) Robotics and Image processing : P.A. Janakiraman - Mc Graw - Hill. 1995.
- (4) Robotics ( Control , Sensing , Vision & Intelligence ) : K.Sfu, R.C.Gonzaler, C.G.Glee Mc Graw - Hill. 1995.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

## 2.2 IC 822 IC : PLANT AUTOMATION

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1.	<b>INTRODUCTION:</b> Automation- Basic functions, Historical development, current trends in process plants.
2.	<b>MODELLING AND SIMULATION FOR PLANT AUTOMATION:</b> Requirement, uses of systems simulation and modelling, mathematical model building, evaluation and improvement, modern tools, application and future perspectives.
3.	<b>INDUSTRIAL CONTROL APPLICATIONS:</b> Objectives, Automation strategy and control of: Cement plant, power plant, water treatment plant, irrigation canal management, steel plant, petrochemical plant.

### References:

- (1) Computer Based Industrial Control By Krishna Kant - by Prentice Hall of India, 1998
- (2) Process Control : by Liptak , Oxford/Butterwork/ Heinmann ltd., 3rd. edi., 1999
- (3) Principal of Process Control : by D. Patranabis, Tata Mcgrahill
- (4) Shreve's Chemical Process industries : by George T. Austin , Mcgrawhill international, 3rd ed.
- (5) Outlines of chemical technology for the 21st century. : by .gopala rao, marshall sitting, East west pub. 3rd edi.
- (6) Advanced Process Control and Information Systems for the Process Industries : by Les A. Kane , Gulf pub., 1st edi. , 1999.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

## 2.3 IC 823 IC : PROCESS SYSTEM ANALYSIS

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1	<b>FUNDAMENTALS OF MATHEMATICAL MODELING:</b> - Introduction : Role of Process dynamics & Control, Historical background, Use of mathematical models, Scope of Coverage, Principles of formulation. - Fundamentals Laws : Continuity equation , Energy equation , Equation of motion , Transport equation, Equation of State, Chemical Kinematics
2	<b>MATHEMATICAL MODELS OF CHEMICAL SYSTEM:</b> - Series of Isothermal, Constant -holdup CSTRs . - CSTR with variable holdups. - Two heated tanks, - Gas phase pressurised CSTR, - Non isotheramal CSTR, - - Single Component Vaporizer, - Multi Component flash drum, - Batch reactor , - Ideal binary distillation column, - Multi component non ideal distillation column.
3	<b>LINEAR OPEN LOOP SYSTEM:</b> - Response of firs-order system and first order system in series - Physical examples of first order system - Higher order system ( Second Order ) and transportation lag.
4	<b>LINEAR CLOSED LOOP SYSTEM:</b> - Control Sysytem, - Controllers and final control elements,
5	<b>COMPUTER IN PROCESS CONTROL :</b> - Digital Computer simulation of control system, - Microprocessor based controlling & distribution control schem.

### References:

- (1) Process system analysis and control : By Donald R. Coughanowr.- Mcgrawhill international , II nd Edition ,
- (2) Process Control : By Thomas E. Malin ( Designing and control system for dynamics performances)
- (3) Process Control : By Peter Harriot - Mcgrawhill international , 1st edition ,
- (4) Process Modeling, Simulation & Control for Chemical Engg. : By William L. Luyben – Mcgrawhill international, II nd Edition

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

## 2.4 IC 824 IC : FUZZY LOGIC CONTROL & NEURAL NETWORK

	Lecture	Tutorial	Practical
Teaching Hours	3	0	0
Examination Scheme Marks	100	0	Cont. Evaluation : 00 Examination : 00

1	INTRODUCTION OF FUZZY LOGIC: - Review of crisp set theory, - Basic concept of fuzzy sets, - fuzzy operation on sets.
2	FUZZY LOGIC CONTROL PRINCIPLE: - Definition and terminology , -Fuzzy relations, -Fuzzy conditional statement, -Fuzzy rules , -Fuzzy Algorithm, -Functional Diagram
3	FUZZY LOGIC CONTROL SYSTEM : -Fuzzy logic controller, -Fuzzification interface, -Knowledge base, -Decision Making Logic,-Defuzzification interface , -Design of fuzzy logic controller, -Functional diagram approach, -Developing fuzzy model, -performance comparison with conventional controller, -Stability analysis of fuzzy control system.
4	FUNDAMENTAL CONCEPTS OF ARTIFICIAL NEURAL NETWORK: - Biological neurons and their artificial models,-Models of artificial neural network, -Neural network learning rules and overview, - Neural processing, Single layer perception Classifiers.

### References :

- (1) Fuzzy Control and Fuzzy System : by John Wiley, 1989.
- (2) Fuzzy Set theory and application : by H.Z. Zimmermann - 2nd Edition.
- (3) An Introduction to Fuzzy Control : by D. Drainbor, H. Hellendoor , M. Reinfrank -2nd edition.
- (4) Fuzzy sets, Uncertainty and Infromation : by George J. Klir , Prentice Hall of India, 1991
- (5) Neural Networks & Fuzzy systems by Bart Kosko, Prentice Hall of India, 1997
- (6) Fuzzy - Neural control principles, algorithms & application by John Nie & Derek Linkens by Prentice Hall of India, 1998.

# VEER NARMAD SOUTH GUJARAT UNIVERSITY

B.E.IV (IC)

Semester - VIII

PROJECT: IC 806 IC

	Lecture	Tutorial	Practical
Teaching Hours	0	0	8
Examination Scheme Marks	-	-	Cont. Evaluation 80 Examination 120

Under the subject, student is supposed to carry out project assembly, final testing , take result and draw conclusion of the project started in Part-I and complete the detailed report about the whole project including the application aspect.

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B.E.IV (IC)

Semester - VIII

SEMINAR : IC 807 IC

	Lecture	Tutorial	Practical
Teaching Hours	0	2	0
Examination	-	0	Cont. Evaluation 20
Scheme Marks			Examination 30

Student is required to go to library and search the material from journals and reference books to prepare comprehensive report under the guidance of faculty on a particular recent development in the field of instrumentation & control.

The term work will consist of a report prepared by every student on the seminar topic allotted to them and oral presentation.